# Is Optimized Design of Satellites Possible?

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ABSTRACT: The design of satellites is most of the time a legacy of traditional architectures that are already flight-proven. This conservative view leads very often with over-specifications and misfit with the mission scope. In doing so, the space community prevents itself from thinking in the opposite way, that is to say to start from requirements and then to design the best optimized architecture. This paper proposes to study an innovative approach based on reliability optimization.

#### **1 INTRODUCTION**

#### 1.1 Overview

Optimization of the satellite architecture is an interesting option in case of the development of a constellation, because the high number of satellites allows a return on investment for this effort.

As an example, we propose to study a simple micro-satellite of the Myriade type and to follow two consecutive steps: first, we will build a simplified model of the satellite internal architecture (platform only, not payload, in order to reuse our study results on various missions), taking into account all its main sub-systems:

- Attitude and Orbit Control
- Propulsion
- Thermal regulation
- Power supply
- On-board processing
- Telecommunications etc...

This may seem a difficult task, considering that satellites have a very complex architecture with a lot of different equipments and redundancies. However, it is possible to build a reliability model of the architecture of one satellite thanks to Reliability Data Blocks, markovian graph or matrix, Fault Trees and redundancies formulas. The reliability prediction of each function (composed of redundant equipments if necessary) is computed with standard exponential law hypothesis. The failure rates data sources are typical in-field performance lessons learned or results of analytic predictions but not real figure for confidentiality constraints.

Then, the second step will consist in applying optimisation techniques based on genetic algorithms and non-linear simplex on this reliability model in order to find the best trade-off between costs and performances. Innovative variant of architectures are expected compared to traditional design and the associated benefits in terms of costs will be evaluated, in relative compared to arbitrary prices used for the study.

#### 1.2 Methodology

The reliability of the platform satellite model is computed thanks to markovian techniques associated to Fault-Tree, because each function is considered necessary to the good functioning of the satellite. Nevertheless, each function can include redundancies in itself.

The optimization technique is based on genetic algorithms. Faure et al (2006), Cabarbaye et al (2006).

The software tools are respectively SUPERCAB and GENCAB of the Cab Innovation company.

Based on a hybrid method associating Genetic Algorithms (Goldberg 1994), Differential Evolution (Feoktistov 2004) and nonlinear Simplex (Nelder Mead algorithm), the principle of this generic tool is illustrated by figure 4 (Cabarbaye 2003). Composed of various parameters (genes) of type real, integer or binary, the chromosomes are subjected to random mutation, crossings and differential evolutions (summation of a gene of chromosome with the difference between same genes of two other chromosomes). After selection, the best elements of the population can be improved at the local level by several steps of Simplex. This hybridization of total and local techniques, which can be possibly parameterized, allows making the tool robust to the diversity of the problems defined by the user on a sheet of spreadsheet. Thus the Differential Evolution will be generally more effective to treat a convex function

**GENCAB** 

Standard or

personalized

adjustment

B (

*Configuration of parameters (binary, integer, real)* 

Function of evaluation

Result of evaluation

+ Constraints

but will present the disadvantage, for others, simultaneously to exploit the whole of genes.

Figure 1. Principle of

The genetic algorithm is then coupled with an algoevaluation based rithm in that case, on Markovian and fault-tree process, allowing to com-

pute the satellite reliability.



Figure 2: Coupling

# 2 RELIABILITY MODEL

## 2.1 Main parameters

The main parameters are in the satellite model:

- Equipments
- Failure Rate expressed in FIT (10<sup>-9</sup> failure per hour) in ON or OFF mode
- Number of equipments
- Kind of redundancy (active, passive or none)
- Rate of utilization

For each equipment, the reliability is computed for a time duration: we chose 5 years in this example. The reason why is that it is an interesting perspective to push the limit of this satellite platform that was ini-



The reliability of the series platform at 5 years is evaluated to 0.6 approximately. See Table 1.

#### the tool

tially intended to operate for 2 years maximum (but proved much superior infield lifetime).

EQUIPMENTS	Failure	Nb	Kind of	Failure	Utilization	Unit cost	Quality	Reliability
	rate		redundancy	rate	rate	high quali.	Level	T (years) =
	ON (fit)		-	OFF(fit)	r (%)	k€		ຶ 5 ໌
Power Supply	1000		serie			100	1	0,95714537
Solar Array	100	Γ	série					0,99562958
Battery	230	Γ	série					0,98997657
	100	Ι	active 9/10					0,99916028
		Γ						
Potential SPF (Central Computer)	40	Γ	série					0,99824953
I/O 1	500	Γ	série					0,97833806
I/O 2	500	Γ	série					0,97833806
TM/TC - clock	100	Γ	passive 1/2					0,99998948
TM/TC - I/F	100	Γ	passive 1/2					0,99998948
TM/TC - I/F +FPGA	200	Γ	série					0,99127826
TM/TC - I/F Telemetry	100	Ι	passive 1/2					0,99998948
CPU- Flash Memory	200	Ι	active 2/3			10	1	0,99977312
CPU- FRAM	200	Γ	active 1/2					0,99992393
CPU - FPGA,T805,DRAM	300	1	série			20	1	0,98694595
CV1 - DC/DC chain	500	Γ	passive 1/2					0,99974022
CV1 - PPU DC/DC	50	T	série					0,9978124
UCM	300	Γ	série					0,98694595
Memory component	70	Γ	série					0,99695992
		Γ						
S Band emitter	800	Γ	passive 1/2		2,00%	50	1	0,99998427
S Band receiver	1100	Γ	active 1/2					0,99778745
S Band antenna and filter	30	2	série					0,99737545
Solar Sensor	10	3	série					0,99868686
		T						
Gyrometers	800	3	serie			20		0,90021649
Propulsion	1500	Γ	série		1,00%			0,99286428
		Γ						
Reaction Wheels	500	4	serie			40		0,91612725
		Γ						
Magneto Torque Bar	10	3	série					0,99868686
Magnetometer	400	Γ	série					0,98263258
		Γ						
Star sensor (electonics)	1100	1	serie			50		0,95296224
Star sensor (optical head)	300	1	serie			20		0,98694595
X Band telemetry unit	500	Ι	série		2,00%			0,99741914
X Band antenna and filter	20	Ι	série					0,99912438
GPS	2000	Ι	serie			30		0,91612725
liscell. (Pyro,wiring,thermal regulation	200	Ι	série					0,99127826
\$	SATELLIT	ΓΕ ΡΙ	ATFORM					0,58769724

Table 1. Reliability model of the generic satellite platform

## **3 OPTIMIZATION**

## 3.1 *Objective*

It is interesting to check if the potential of this platform can be stretched to a Reliability of 0.8 at 5 years, in order to use it for more operational missions that require a much better availability.

# 3.2 Rationale

In the reliability model of the satellite platform, it is easy to spot the main contributors to the global unreliability.

Targeting these equipments, our objective is to improve their reliability thanks to:

- Redundancy
- Components quality level (associated with cost)

In that scope, the satellite platform configuration can be seen as a set of parameters, such as a chromosom, and the optimization algorithm will find the one that provided the smallest cost within the reliability target objective.

# 3.3 Targets of the optimization

For this example, and not for real data, the targeted equipments are:

- power supply system
- flash memory
- main processor
- S-Band emitter
- Gyrometers
- Reaction wheels
- Star sensor: main electronic + optical heads
- GPS

The genetic optimization will be applied precisely to the listed equipments in this respect:

- For active or passive redundancies (M among N), the number N will be optimized.
- The components quality level will be optimized. The following hypothesis are exposed in Table 2.

EQUIPMENTS	Failure rate	ND	Kind of redundancy	Failure rate	Utilization rate	Unit cost high quali.	Quality Level	Cost	Reliability T (year) =	
	ON (fit)			OFF(fit)	r (%)	k€		k€	5	
Power Supply	3525		Passive 1/2			100	2	100	0,988223573	
Solar Array	100		serie						0,995629578	d the follow-
Battery	110.0	+	serie	-+					0,998336984	
	113,2	+	active 3/10						0,330013100	
		• • • • • • • • • • • • • • • • • • • •				+			0 998336984	ncy 1 among
	500	• • • • • • • • • • • • • • • • • • • •	vérie			+			0,00000004	<i>. . .</i>
1/0.2 (08C)	500	+	série	-+	+				0.978338064	
TM/TC - OCXO (OBC)	100	+	passive 1/2						0.999989481	ality level 2
TM/TC - PIC rep (OBC)	100		passive 1/2						0,999989481	uality level 1
TM/TC - I/F +FPGA (OBC)	200		série		1	1			0,991278257	vality laval 2
TM/TC - PIC TMD (OBC)	100	1	passive 1/2						0,999989481	lanty level 5
CPU- Flash Memory (OBC)	<b>600</b>		active 2/3			10	2	15	0,998016609	y 1 among 2
CPU- FRAM (OBC)	200		active 1/2						0,999923931	Jundancy 3
CPU - FPGA,T805,DRAM (OBC).	300		série			20	1	20	0,986945953	fundancy. 5
CV1 - DC/DC chain (OBC)	500		passive 1/2						0,999740224	
CV1 - PPU DC/DC (OBC)	50		série						0,997812396	) redundancy
	300		série						0,986945953	, i l
Memory component (red)	[/0		serie						0,996929918	cuve redun-
C Pand omitter	0300				2 00%	50	2	20	0 000267740	
S Band receiver	1160	•••••	passive 172 police 172		2,00%	+			0,550507745	ong ?
S Band antenna and filter	20		ocuve 172			+			0,007040002	ong 2
Solar Sensor	9		série		+				0,998818099	
		+							+	1 easily by a
GYRO	800	3	Passive 1/2			20		40	0,998024441	a casiry by a
Propulsion	1524	· · · · · ·	série		1,00%	1			0,992750524	
		1								
Reaction Wheels	500	1	Active 3/4			40		160	0,99726522	and is a rali
										ons is a ren-
Magneto Torque Bar	7	3	série						0,999080623	l cost of 518
Magnetometer	410		série						0,982202284	nized equip
										mzeu equip-
Solar sensor (electonics)	1110		Passive 1/1			50		50	0,952544932	
Solar sensor [optical head]	324		Active 1/1		0.00%	20		20	0.98590902	e series con-
X Band telemetry unit	530		serie		2,00%				0,997264496	.1: .1. :1:
A Band antenna and filter	20		serie			·····			0,999124384	mability per-
Missell (Pure wiring thermal regulation)	1322	·   · · · ·	Passive 1/2						0,336324463	
terrategulation) €	PI.		BM					518	0,332403743	
Ψ	FL	~110	1.00			I	└── <b> </b> ♥ ─	4	0,000210704	

Objective: 0,8

EQUIPMENTS	Failure	Nb	Kind of	Failure	Utilization	Unit cost	Quality		Reliability
	rate		redundancy	rate	rate	high quali.	Level	Cost	T (year) =
	ON (fit)		_	OFF(fit)	r (%)	k€		k€	5
Power Supply	3000		Passive 1/2			100	2	100	0,99133358
Solar Array	100		série		T				0,99562958
Battery	230		série		T				0,98997657
	100		active 9/10		Ι				0,99916028
	I				Ι				
Potential SPF (Central Computer)	40		série		I				0,99824953
I/O 1	500		série		Ι				0,97833806
I/O 2	500		série		Ι				0,97833806
TM/TC - clock	100		passive 1/2		Ι				0,99998948
TM/TC - I/F	100		passive 1/2		Ι				0,99998948
TM/TC - I/F +FPGA	200		série		Ι				0,99127826
TM/TC - I/F Telemetry	100	1	passive 1/2		Τ				0,99998948
CPU- Flash Memory	600		active 2/3		Τ	10	2	15	0,99801661
CPU- FRAM	200	1	active 1/2		Τ				0,99992393
CPU - FPGA,T805,DRAM	300		série		Τ	20	1	20	0,98694595
CV1 - DC/DC chain	500	Ι	passive 1/2		Τ	[		Γ	0,99974022
CV1 - PPU DC/DC	50	Ι	série		Τ	[		Γ	0,9978124
UCM	300	Ι	série		Τ	[		Γ	0,98694595
Memory component	70	Ι	série		Τ	[		Γ	0,99695992
	[				1				[
S Band emitter	8000		passive 1/2		2,00%	50	3	20	0,99848139
S Band receiver	1100		active 1/2		T				0,99778745
S Band antenna and filter	30	2	série		T				0,99737545
Solar Sensor	10	3	série		T				0,99868686
	1				T				[
Gyrometers	800	3	Passive 1/2		1	20		40	0,99802444
Propulsion	1500		série		1,00%				0,99286428
	1				T				[
Reaction Wheels	500		Active 3/4		T	40		160	0,99726522
	Γ	Ι			Τ	[		Γ	
Magneto Torque Bar	10	3	série		Τ	[		Γ	0,99868686
Magnetometer	400		série		1				0,98263258
	1				T				[
Star sensor (electonics)	1100		Passive 1/1		T	50		50	0,95296224
Star sensor (optical head)	300	Ι	Active 1/1		Τ	20		20	0,98694595
X Band telemetry unit	500	Ι	série		2,00%	[		[	0,99741914
X Band antenna and filter	20	T	série		Τ	[		[	0,99912438
GPS	2000	T	Passive 1/2	I	Τ	30		60	0,99602952
liscell. (Pyro,wiring,thermal regulation	200	T	série		Τ	I		Γ	0,99127826
\$	SATELLI	TE PI	LATFORM					518	0,79605702
							-		

Table 3. Configuration resulting from the optimization

## 4 CONCLUSION

Facing the increase in the use of COTS technology, intrinsically more sensitive to radiations in the case of the micro-processors, one candidate solution is to implement more redundancies.

Towards an evolutionary model of satellites design: it might be the next cutting edge methodology for optimized design, based on reliability, costs or power consumption, mass etc...The optimized parameters have practically no limits, and the increase in computing power will allow to deal with models in which every parameter will be subject to optimization.

The techniques and the way of thinking exposed in this paper are currently being put into practice at the French Space Agency (CNES) on future project designs at satellite and system level: constellations (deployment and maintenance strategy), ground segment infrastructure (maintenance of repairable systems).

## **5** REFERENCES

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